



Memory-Friendly Lock-Free Bounded Queues



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Motivation

How to improve FIFO queues performance?

- Reduce the number of failed CAS (e.g., by replacing them with FAA operations)
- Make the algorithm more *memory-friendly*

How to achieve *memory-friendliness*?

- For unbounded queues: allocate memory in chunks (constructing a linked queue on them)
- For bounded queues: re-using a single pre-allocated array with the corresponding size
- Use the fewest descriptors or metadata possible

Is there a lock-free *bounded* queue that uses $O(1)$ additional memory (no metadata or descriptors)?

Bounded Queue

Bounded queue is a FIFO queue which is limited in capacity:

- `offer(e)` inserts the element `e` and returns `true` if the queue is not full, returns `false` otherwise
- `poll()` retrieves and returns the first element if the queue is not empty, returns `null` otherwise

Algorithm Assumptions

- All inserting elements should be distinct (many software systems use queues for unique tasks or identifiers)
- We have an unlimited supply of versioned `null` values, so that we can use different `null`-s for different rounds (can be achieved by stealing one bit from values)

These assumptions guarantee the lack of the ABA problem on array cells updates.

Implementation

```
class BoundedQueue<T>(val CAPACITY: Int) {
    val a: T[] = Array(CAPACITY) // a[i] = ⊥₀
    var offers: Long = 0L
    var polls: Long = 0L
}

fun offer(e: T): Bool = while (true) {
    o := offers
    p := polls
    // is 'o' still the same?
    if o != offers: continue
    // is the queue full?
    if o == p + CAPACITY: return false
    // try to perform the offer
    i := o % CAPACITY
    round := o / CAPACITY
    success := CAS(&a[i], ⊥₍round₎, e)
    // increment the counter
    CAS(&offers, o, o + 1)
    if success: return true
}
```

```
fun poll(): T? = while (true) {
    p := polls
    o := offers
    i := p % CAPACITY
    e := a[i]
    // is 'p' still the same?
    if p != polls: continue
    // is the queue empty?
    if p == o: return null
    // is the element already taken?
    nextRound = p / CAPACITY + 1
    if e == ⊥₍nextRound₎ {
        CAS(&polls, p, p + 1) // helping
        continue
    }
    // try to retrieve the element
    success := CAS(&a[i], e, ⊥₍nextRound₎)
    // increment the counter
    CAS(&polls, p, p + 1)
    if success: return e
}
```

Theoretical Result

Def. An implementation is *value-preserving* if inserting values are subject only to reads, writes, and equality checks (including the ones during CAS-s). Thus, bit stealing is not allowed.

Def. Consider the arbitrary reachable state. Let x_1, \dots, x_n be the values that do not occur in the memory cells. Suppose we sequentially perform `offer(x_1)`, ..., `offer(x_n)` and reach the state M of the memory. An algorithm is *argument-independent* if after changing `offer(x_i)` to `offer(v)` all the memory cells with x_i in M now store v .

Theorem. If there are p processes working on value-preserving and argument-independent queue, any obstruction-free algorithm needs at least $CAPACITY + O(p)$ memory cells.

Remarks

- The bound from the Theorem can be achieved with a lock-free algorithm on re-usable descriptors.
- As well as `null` values, elements should be distinct only between different rounds and can coincide during the same one.
- If the presented algorithm can be improved so that it supports indistinguishable either `null` or inserting values, it should be simple (but impossible) to solve the second problem.

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